# Modelling the Wave-Induced Collisions of Ice Floes

Lucas J. Yiew

Thesis submitted for the degree of

Doctor of Philosophy

in

 $Applied\ Mathematics$ 

at

The University of Adelaide

Faculty of Engineering, Computer and Mathematical Sciences

School of Mathematical Sciences



February 22, 2017

## Contents

$\mathbf{Si}$	Signed Statement			
A	cknov	wledgen	nents	x
$\mathbf{A}$	bstra	$\operatorname{\mathbf{ct}}$		xii
1	Intr	oductio	on	1
	1.1	Backgro	ound and context	. 1
	1.2	Existing	g theoretical models	. 3
	1.3	Relevan	nt laboratory experiments	. 7
	1.4	Scope o	of thesis	. 9
2	Sing	gle-floe	experiments	11
	2.1	Objecti	ves	. 11
	2.2	Experir	mental method	. 12
		2.2.1	Wave basin facility	. 12
		2.2.2	Floe properties	. 13
		2.2.3	Coordinate system	. 13
		2.2.4	Instrumentation	. 15
		2.2.5	Test conditions	. 16
		2.2.6	Data processing	. 17
	2.3	Results		. 20
		2.3.1	Response amplitude operators	. 20
		2.3.2	Drift velocity	. 26
	2.4	Summa	ry	. 29
3	The	slope-s	sliding model	31

	3.1	Equation of motion	32
	3.2	Solution method	33
	3.3	Phase space	35
	3.4	Drag and added mass coefficients	38
		3.4.1 Effect on surge	38
		3.4.2 Effect on drift	39
	3.5	Long-wavelength approximation	11
	3.6	Comparison with single-floe experiments	12
	3.7	Summary	14
4	The	e potential-flow model 4	16
	4.1	Formulating the boundary value problem	16
	4.2	The eigenfunction matching method	18
		4.2.1 Diffraction problem	49
		4.2.2 Radiation problems	52
		4.2.3 Analytical and numerical checks	55
		4.2.4 Accuracy and convergence	57
	4.3	Equations of motion	60
	4.4	Analytical proofs in the long-wavelength limit	31
	4.5	Model-data comparisons	62
	4.6	Summary	35
5	Two	o-floe non-rafting experiments	67
	5.1	Objectives	67
	5.2	Experimental method	68
		5.2.1 Floe properties	68
		5.2.2 Setup and instrumentation	38
		5.2.3 Test conditions	70
		5.2.4 Data processing	71
	5.3	Results	73
		5.3.1 Collision regimes	73
		5.3.2 Collision frequency and velocity	78
		5.3.3 Surge	31
	5.4	Summary	35

6	The	two-floe collision model	<b>37</b>	
	6.1	Collision algorithm	87	
	6.2 Simulating floe displacements		91	
		6.2.1 Equation of motion	91	
		6.2.2 Transients in wave forcing	92	
		6.2.3 Mooring coefficients	93	
		6.2.4 Hydrodynamic coefficients	95	
	6.3	Comparison with two-floe experiments	98	
	6.4	Summary	)2	
7	Exte	ension to rafting	)3	
	7.1	Two-floe rafting experiments	)3	
		7.1.1 Experimental method	)3	
		7.1.2 Results	)9	
7.2 Extending the two-floe collision model		Extending the two-floe collision model	16	
		7.2.1 Criteria for rafting	16	
		7.2.2 Tuning parameters	18	
	7.3	Model-data comparisons	21	
	7.4	Summary	24	
8	Con	clusions 12	26	
Bi	Bibliography 131			

## List of Tables

2.2.1	Summary of test matrices for single-floe experiments	17
4.2.1	Wetted surface boundary conditions for radiation problems	53
5.2.1	Summary of test matrix for two-floe non-rafting experiments	70
7.1.1	Summary of test matrix for two-floe rafting experiments	106

## List of Figures

2.2.1	Image of the MTB	12
2.2.2	Photo and schematic of Floe B	13
2.2.3	Schematic plan view of the MTB	14
2.2.4	Schematic of Floe NB, coordinate system and oscillatory motions	16
2.2.5	Example of motions in the z-direction	18
2.2.6	Example of motions in the $x$ -direction	19
2.3.1	Raos for Floe B for Matrix 1	21
2.3.2	Changes to the wave field in the long- and short-wavelength regime	22
2.3.3	Raos for Floe B and Floe NB for Matrix 1	23
2.3.4	Deviation of surge RAO of Floes B and NB from the mean for Matrix 2,	
	as a function of wave steepness	25
2.3.5	Example of overwash increasing with wave steepness	26
2.3.6	Calculating the drift velocity	27
2.3.7	Drift velocities of Floe B and NB from Matrix 1 and 2, with respect to	
	the phase velocity, as a function of wave steepness	28
3.0.1	General wave parameters	32
3.2.1	Example of a floe's displacement predicted by the slope-sliding model	34
3.3.1	Phase diagrams for zero drag case	36
3.3.2	Phase diagram when $c_d = 3 \times 10^{-4}$	38
3.4.1	Effect of the drag and added mass on surge	39
3.4.2	Effect of drag and added mass on drift velocity	40
3.5.1	Full numerical solution of the slope-sliding model versus long-wavelength	
	approximation of surge	42
3.6.1	Comparison of surge RAOs from single-floe experiments and slope-sliding	
	model	43

4.1.1	Two-dimensional Cartesian coordinate system and geometry of water-	
	floe domain	47
4.2.1	Boundary conditions for surge problem	55
4.2.2	Comparison between potential-flow model and results from Black et al.	
	(1971)	56
4.2.3	Absolute values of potentials and horizontal velocities along the vertical	
	fluid interface for the diffraction problem	58
4.2.4	Error between potentials and velocities, as a function of number of modes.	59
4.2.5	Convergence of reflected and transmitted coefficients	59
4.5.1	Comparison of surge RAOs predicted by the potential-flow model, slope-	
	sliding model and experimental data	63
4.5.2	As per Figure 4.5.1 but for heave.	63
4.5.3	As per Figure 4.5.1 but for pitch	64
4.5.4	As per Figure 2.3.4, but for deviation of experimental data from the	
	potential-flow model	65
5.2.1	Photo of Floes F and R in their initial positions	68
5.2.2	Schematic plan view of the MTB for two-floe experiments	69
5.2.3	Example of falsely acquired collision events	72
5.3.1	Collision regimes as a function of incident wave amplitude and nondi-	
	mensional wavelength	74
5.3.2	Motions of Floes F and R in the x-axis	75
5.3.3	Images of floes and surrounding wavefields	77
5.3.4	Mean collision frequencies and velocities as functions of incident wave	
	frequency.	79
5.3.5	Surge RAOs of Floe F and R in comparison to that of Floe B from the	
	single-floe experiments	81
5.3.6	Example of how the relative surge is calculated	82
5.3.7	Normalised relative surge as a function of nondimensional wavelength	83
5.3.8	Examples of collisions caused by surge and drift	84
6.1.1	Visualising floes as 1-D planes	88
6.1.2	Flowchart summarising the collision algorithm	90

6.2.1	Parameterised transient and steady-state wave profiles in comparison
	to measured wave profile
6.2.2	Effect of spring and damping constants on horizontal displacements 94
6.2.3	Effect of the drag coefficient on floe displacements when surge is dominant. 95
6.2.4	Effect of drag coefficient on floe displacements when collisions occur 96
6.2.5	Empirically determined drag coefficients as functions of incident wave
	frequency and wave amplitude
6.3.1	As with Figure 5.3.4 but with model predictions included 100
6.3.2	Example of the collision model not being able to simulate floe behaviour
	in short wavelengths
7.1.1	Image of the DUT wave basin facility
7.1.2	Schematic plan view of the DUT wave basin during the two-floe rafting
	experiments
7.1.3	Photo of rafting experiment setup
7.1.4	Image of the magnetic motion tracking system
7.1.5	Measured wave amplitudes
7.1.6	Collision and rafting regimes as a function of target incident wave am-
	plitude and nondimensional wavelength
7.1.7	Example of long contact rafting
7.1.8	Example of short contact rafting
7.1.9	Normalised relative surge as a function of nondimensional wavelength 114
7.1.10	Calculating the overlap
7.1.11	Normalised overlap as a function of nondimensional wavelength 116
7.2.1	Floes visualised as 2-D cross-sections
7.2.2	Flowchart for collision and rafting algorithm
7.2.3	Effect of the spring, damping and drag coefficients on horizontal motions.119
7.2.4	Floe responses simulated using the mooring coefficients of the non-
	rafting and rafting experiments
7.3.1	As with Figure 7.1.6 but with model predictions overlaid onto experi-
	mental data
7.3.2	Example of rafting predicted by the collision model with poor agree-
	ment for displacements

### Signed Statement

I certify that this work contains no material which has been accepted for the award of any other degree or diploma in my name in any university or other tertiary institution and, to the best of my knowledge and belief, contains no material previously published or written by another person, except where due reference has been made in the text. In addition, I certify that no part of this work will, in the future, be used in a submission in my name for any other degree or diploma in any university or other tertiary institution without the prior approval of the University of Adelaide and where applicable, any partner institution responsible for the joint award of this degree.

I give consent to this copy of my thesis, when deposited in the University Library, being made available for loan and photocopying, subject to the provisions of the Copyright Act 1968.

I also give permission for the digital version of my thesis to be made available on the web, via the University's digital research repository, the Library Search and also through web search engines, unless permission has been granted by the University to restrict access for a period of time.

SIGNED: DATE:			
	SIGNED:	DATE	

## Acknowledgements

I would like to express my deepest gratitude to my supervisors Dr. Luke Bennetts and Assoc. Prof. Mike Meylan for their support and guidance. Dr. Bennetts has been an exemplary role model and has been generous in providing much of his time and effort to guide me in my research over the last three years. I must thank him for assisting me with a smooth transition from engineering to mathematics.

Assoc. Prof. Meylan has also been instrumental to the progress of my research. It was a privilege to work with him in Newcastle on a number of occasions.

I must acknowledge the support of Prof. Giles Thomas and Assoc. Prof. Guoxing Huang (through the recommendation of Assoc. Prof. Adrian Law), who provided us with the facilities and funds to perform wave basin experiments at the Australian Maritime College and the Dalian University of Technology. I am deeply appreciative for the technical assistance from Benjamin French, Tian Yong Jin, Song Yue and Sun Zhen Xiang during the experiments.

I would also like to thank Prof. Hayley Shen and Assoc. Prof. Agnieszka Herman for allowing me the opportunity to share my research with them.

Finally, I am thankful for the support and love from my parents, the Ki family, and most of all my wife, Grace, who has been remarkably longsuffering and patient with me throughout my studies, all the while encouraging and motivating me to better myself each day.

This thesis contains excerpts which have been published in the following journals and conference proceedings:

Yiew, L. J., Bennetts, L. G., Meylan, M. H., French, B. J., & Thomas, G. A. (2016). Hydrodynamic responses of a thin floating disk to regular waves. *Ocean Modelling*, 97, 52–64.

Meylan, M. H., Yiew, L. J., Bennetts, L. G., French, B. J., & Thomas, G. A. (2015). Surge motion of an ice floe in waves: comparison of theoretical and experimental models. *Annals of Glaciology*, 56(69), 155–159.

Bennetts, L. G., Yiew, L. J., Meylan, M. H., French, B. J., & Thomas, G. A. (2014). An experimental model of non-rafting collisions between ice floes caused by monochromatic water waves. *Proceedings of the 19th Australasian Fluid Mechanics Conference*.

#### Abstract

The wave-induced collisions and rafting of ice floes are investigated experimentally and theoretically. Results from a series of wave basin experiments are presented. Ice floes are simulated experimentally using thin plastic disks. The first round of experiments focusses on measuring the oscillatory surge, heave, pitch and drift motions of solitary floes. The second and third rounds of experiments record the motions of two adjacent floes. Rafting is suppressed in the second round, and allowed in the third round. Collision and rafting regimes are identified, and collision behaviours are quantified over a range of incident wavelengths and wave amplitudes.

Two mathematical models are proposed to model the wave-induced motions of solitary floes. The first is based on slope-sliding theory, and the second is based on linear potential-flow theory. Both models are validated using results from the single-floe experiments. Model-data comparisons show that the slope-sliding model is valid in the long-wavelength regime, and potential-flow model is more accurate in shorter wavelengths.

A two-floe collision model is then developed to replicate the conditions of the two-floe experiments. Slope-sliding theory is used to model floe motions. A time-stepping algorithm is implemented to determine the occurrence of collision and rafting events. Predicted collision behaviours are compared with results from the two-floe experiments. Good agreement is attained in incident waves of intermediate to long wavelengths.