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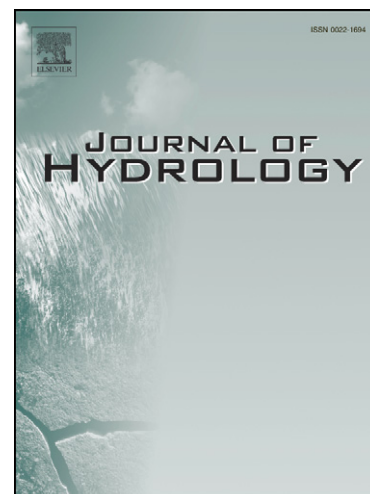
Detection of non-stationarity in precipitation extremes using a max-stable process model

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1 **Detection of non-stationarity in precipitation extremes using a max-stable process**
2 **model**

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6 [1] Non-stationarity in extreme precipitation at sub-daily and daily timescales is assessed
7 using a spatial extreme value model based on max-stable process theory. This approach,
8 which was developed to simulate spatial fields comprising observations from multiple point
9 locations, significantly increases the precision of a statistical inference compared to standard
10 univariate methods. Applying the technique to a field of annual maxima derived from 30 sub-
11 daily gauges in east Australia from 1965 to 2005, we find a statistically significant increase of
12 18% for 6-minute rainfall over this period, with smaller increases for longer duration events.
13 We also find an increase of 5.6% and 22.5% per degree of Australian land surface
14 temperature and global sea surface temperature at 6-minute durations, respectively, again
15 with smaller scaling relationships for longer durations. In contrast, limited change could be
16 observed in daily rainfall at most locations, with the exception of a statistically significant
17 decline of 7.4% per degree land surface temperature in southwest Western Australia. These
18 results suggest both the importance of better understanding changes to precipitation at the
19 sub-daily timescale, as well as the need to more precisely simulate temporal variability by
20 accounting for the spatial nature of precipitation in the statistical model.

21 **1. Introduction**

22 [2] The question of how extreme precipitation will change under a future climate represents
23 an urgent research problem, not least because of the significant societal impacts that would
24 result from an increase in precipitation-induced flooding [Wilbanks *et al.*, 2007]. To better
25 constrain future projections, an important line of evidence comes from statistical assessments
26 of changes to extreme precipitation in the observational record, with a large number of such
27 studies recently having been published [e.g. Alexander *et al.*, 2006; Frich *et al.*, 2002;
28 Groisman *et al.*, 2005]. These studies, which typically focus on the detection of trends from
29 daily gauged precipitation data, find increases in extremes throughout most of the world
30 including in many locations where mean annual precipitation is decreasing, with these
31 changes generally being of similar sign but greater in magnitude than expected from climate

32 model simulations [Allan and Soden, 2008; Allan et al., 2010]. Nevertheless, there remains
33 significant uncertainty associated with quantifying long-term trends from these limited
34 observational records [O'Gorman and Schneider, 2009], particularly for smaller spatial
35 domains and at sub-daily timescales.

36 [3] Despite the obvious importance of such observational studies, surprisingly little attention
37 has been given in the climate literature to the development of statistical methods that are able
38 to provide inference on observed changes in extremes at the necessary levels of precision. In
39 particular, assuming by way of example that extreme precipitation will scale at a rate of
40 $7\%/^{\circ}\text{C}$ in proportion to the water holding capacity of the atmosphere [Min et al., 2009;
41 O'Gorman and Schneider, 2009; Trenberth et al., 2003], and considering a global warming
42 trend over the 20th century of about 0.74°C [IPCC, 2007], methods of detection would need
43 to be sensitive to changes in the order of only 5% over the historical record. Univariate
44 methods applied to point precipitation data generally are not appropriate in this context: when
45 analysing the statistical power of four approaches to modelling trends in extreme rainfall
46 (including annual maxima and r -largest maxima approaches from extreme value theory),
47 Zhang et al [2004] found that such trends would be detected at the 5% significance level in
48 less than 20% of cases [see also Frei and Schar, 2001].

49 [4] To address these deficiencies, many studies use extreme precipitation indices based on
50 averaging over either space or time, in an effort to increase the signal-to-noise ratio and thus
51 improve the detectability of any trends which might be present. For example, based on
52 climate model outputs, Hegerl et al. [2004] find that anthropogenic influences in precipitation
53 can be best detected in an index representing the averages of the 5 or 10 wettest days of the
54 year, with changes to rarer events being more difficult to detect. Similarly, numerous studies
55 have pooled data from multiple locations across some spatial domain [e.g. Alexander et al.,
56 2006; Fowler and Wilby, 2010; Groisman et al., 2005] in order to improve statistical
57 inference, with Min et al. [2009] finding that trends in extreme precipitation might become
58 detectable when pooling data to global or hemispheric scales. Difficulties with this approach,
59 however, include differences in scale (in particular it is often unclear how to standardise the
60 data prior to averaging, with different approaches likely to yield different outcomes) and the
61 development of correct inferential techniques, particularly in the presence of spatial
62 correlation between the original gauged data. Furthermore, local-scale information is lost by

63 pooling the data in this manner, particularly in terms of the marginal distributions of the
64 original point-based gauged data.

65 [5] A more elegant solution involves fitting a spatial extreme value model to multiple point
66 locations within the spatial domain of interest, accounting for both the spatial and temporal
67 variability in model parameters as well as the dependence between individual point-based
68 records [e.g. see discussion in *Aryal et al.*, 2009; *Frei and Schar*, 2001; *Katz*, 2010]. The
69 natural class of model to simulate such data is known as a max-stable process [*de Haan*,
70 1984; *de Haan and Pickands*, 1986; *Resnick*, 1987], which in terms of asymptotic
71 motivations can be directly regarded as the spatial analogue of the univariate generalised
72 extreme value (GEV) distribution. The max-stable model differs from the more commonly
73 used "spatial GEV" model, in which univariate GEV parameters are modelled as a function
74 of spatial location and potentially other covariates. The spatial GEV typically assumes spatial
75 independence of the precipitation process conditional on the model parameters [*Buishand*,
76 1991], which can lead to unrealistic spatial inference and prediction [see *Katz et al.*, 2002 for
77 a discussion of this issue, and Section 2.1 of this paper for an example of the implications of
78 ignoring data-level spatial dependence].

79 [6] Although much of the theory for multivariate max-stable models was derived over 20
80 years ago, computational challenges and the absence of a proper inferential framework for
81 analysing spatial extremes have provided a significant barrier to the wider uptake of the
82 method [e.g. see *Coles*, 1993; *Smith*, 1990 for early work on fitting max stable process
83 models]. However, standard likelihood-based fitting techniques have recently been developed
84 [*Padoan et al.*, 2010], paving the way for their routine implementation in applied research.

85 [7] This study provides one of the first applications of a max-stable process model to simulate
86 both spatial and temporal variability, using a synthetic dataset and two different sets of
87 observational records of annual maximum precipitation in Australia. The objectives of the
88 synthetic study are to highlight the benefits of fitting a spatial model to multiple point
89 locations, assess the implications of spatial dependence between data, and answer the
90 question: how much data is required to derive a given level of inference? Two Australian
91 precipitation datasets are used to demonstrate this model in the detection and attribution of
92 temporal change. The first is the east-Australian sub-daily (pluviograph) precipitation record,
93 which is of interest due to the recent evidence that changes to extremes are most likely to be
94 found in short-duration precipitation events [*Haerter et al.*, 2010; *Hanel and Buishand*, 2010;

95 *Hardwick-Jones et al.*, 2010; *Lenderink and van Meijgaard*, 2008], the importance of sub-
 96 daily rainfall for urban drainage and flood estimation [*Berne et al.*, 2004] and the
 97 abovementioned difficulties associated with detecting change from short observational
 98 records. The second dataset is a longer record of daily-read gauges located throughout
 99 Australia, and is used as an independent dataset for comparison with the pluviograph record,
 100 while also providing additional information at locations where pluviograph data is
 101 unavailable.

102 [8] The remainder of the paper is structured as follows. In the following section a brief
 103 overview is provided of the max-stable process methodology, followed by a synthetic study
 104 which highlights the benefits of using the technique in the detection of trends. In Section 3
 105 we present the data used in the analysis, comprising both daily-read and pluviograph records
 106 across Australia. The results are then presented in Section 4, followed by conclusions in
 107 Section 5.

108 **2. Methodology**

109 [9] In this section we provide a description of max-stable process models and the relevant
 110 statistical fitting procedures, before presenting a synthetic study to assess how much data is
 111 required to result in a particular level of statistical significance of trend detection in extremes,
 112 as related to the strength of spatial dependence between point locations.

113 **2.1 Models for spatial extremes**

114 [10] Classical univariate extreme value theory describes the statistical behaviour of $M_n =$
 115 $\max \{X_1, \dots, X_n\}$ for large n , where X_1, X_2, \dots is a sequence of independent (or weakly
 116 dependent) observations having a common distribution function [e.g. *Leadbetter et al.*, 1983].
 117 For example, X_t might represent the daily precipitation recorded at a particular rain gauge on
 118 day t , and if $n=365$ then M_n would correspond to the annual maximum daily rainfall [e.g.
 119 *Coles*, 2001]. Asymptotic results state that under some regularity conditions (such as
 120 continuity of the underlying distribution function of X_t), normalising sequences $\{a_n\}$ and
 121 $\{b_n > 0\}$ can be found such that

$$\Pr\left(\frac{M_n - a_n}{b_n} \leq z\right) \rightarrow G(z)$$

122 as $n \rightarrow \infty$, for a non-degenerate distribution function G . It follows [e.g. *Jenkinson, 1955; von*
 123 *Mises, 1954*] that G belongs to the Generalized Extreme Value (GEV) family, with
 124 distribution function

$$G(z) = \exp \left\{ - \left[1 + \xi \left(\frac{z - \mu}{\sigma} \right) \right]^{-1/\xi} \right\},$$

125 defined on the set $\{z: 1 + \xi(z - \mu)/\sigma > 0\}$, where μ and $\sigma > 0$ are location and scale
 126 parameters respectively. The shape parameter, ξ , determines the type of tail behaviour:
 127 $\xi < 0$, $\xi = 0$ and $\xi > 0$ correspond to the Weibull, Gumbel (in the limit as $\xi \rightarrow 0$) and
 128 Fréchet sub-families of distributions respectively.

129

130 [11] Although the above theory applies in the general case only in the limit as $n \rightarrow \infty$, in
 131 practice this result allows the GEV distribution to be substituted as an approximation to the
 132 actual distribution of observed block maxima for finite n . For example, the GEV distribution
 133 could be used to model the annual maximum daily rainfall over a number of years [*Coles et*
 134 *al., 2003*]. The unknown normalisation constants, $\{a_n\}$ and $\{b_n > 0\}$, may be absorbed into
 135 the model parameters, which can then be estimated through standard statistical procedures
 136 such as maximum likelihood [*Coles, 2001; Sisson et al., 2006*], probability-weighted (L-
 137 weighted) moments [*Hosking et al., 1985; Kharin and Zwiers, 2000; Perkins et al., 2009*] or
 138 Bayesian inference [*Coles et al., 2003*]. Predictions of future maxima at the point location
 139 can then be made via inversion of the distribution function. Extreme value modelling via
 140 GEV distributions has had much application in the hydrological sciences (see above
 141 references). See e.g. Leadbetter et al. [1983], Resnick [1987] and Coles [2001] for further
 142 discussion and alternative representations of extreme value models.

143 [12] The statistical theory and practice of univariate extremes is well developed. However
 144 many environmental processes have a natural spatial domain. Several authors have proposed
 145 modelling spatially dependent extremes through hierarchical models [e.g. *Sang and Gelfand,*
 146 *2007; Zhao and Chu, 2010*], whereby dependence between neighbouring sites is achieved by
 147 enforcing strong relationships between the GEV parameters at each site. However, this
 148 approach typically assumes that the data are conditionally independent given the parameters,
 149 and as such, the models are unable to account for data-level dependence unless this is
 150 explicitly built into the model. For example, under a stationary environmental process
 151 (whereby the GEV parameters are constant at each site) prediction under the spatial GEV
 152 model effectively assumes independent predictions at each spatial location. Hence an

153 observed 1 in 100-year event (such as a storm) occurring simultaneously over two closely
 154 neighbouring spatial locations will predicatively occur under the spatial GEV model once in
 155 every 100×100 years - a serious underestimate. One alternative approach for modelling
 156 spatial extremes that naturally accounts for spatial data-level dependence is through max-
 157 stable processes.

158 [13] Max-stable processes are a spatial analogue of multivariate extreme value models [*de*
 159 *Haan*, 1984; *de Haan and Pickands*, 1986; *Resnick*, 1987] - a direct extension of the
 160 univariate GEV model into the spatial domain, which goes beyond the limitations of the
 161 spatial GEV model. Max-stable processes provide a general framework for modelling
 162 multivariate extremes with spatial and temporal dependence [*Coles*, 1993; *Padoan et al.*,
 163 2010; *Smith*, 1990]. In analogy with the univariate theory, suppose that $\{X_i(s)\}_{s \in S}$ for
 164 $i = 1, \dots, n$ are now n independent realisations of a continuous process indexed by s , where
 165 $S \subseteq \mathbb{R}^2$ commonly represents the bivariate spatial domain. As before, if the limit

$$\tilde{X}(s) = \lim_{n \rightarrow \infty} \frac{\max_{i=1, \dots, n} X_i(s) - a_n(s)}{b_n(s)}$$

166 exists for all $s \in S$, with normalising constants $a_n(s)$ and $b_n(s) > 0$, then $\tilde{X}(s)$ is a max-
 167 stable process [*de Haan*, 1984]. It follows [*de Haan and Resnick*, 1977] that for a fixed point
 168 in space, s , each one-dimensional marginal distribution belongs to the univariate GEV
 169 family, and that any K -dimensional marginal distribution (i.e. for multiple locations, s)
 170 belongs to the class of multivariate extreme value distributions. In practice, this means that
 171 the resulting parameters $\mu(s)$, $\sigma(s) > 0$ and $\xi(s)$ are now continuous spatial functions to be
 172 estimated. However, unlike spatial GEV models, the max-stable process naturally permits
 173 modelling and prediction with data-level spatial dependence.

174 [14] A useful interpretation of stationary max-stable processes (e.g. with unit Fréchet one-
 175 dimensional "GEV" margins) is the storm profile model [*Schlather and Tawn*, 2003; *Smith*,
 176 1990]. This is based on a Poisson process $\{Y_j, U_j\}_{j \geq 1}$ of "storms" centred at $Y_j \in \mathbb{R}^2$ with
 177 magnitude $U_j > 0$, where each storm has a shape governed by a non-negative, measurable
 178 function $f(y - s)$ such that $\int_{\mathbb{R}^2} f(y - s) dy = 1$ for fixed $s \in S$. For example, f could be a
 179 Gaussian density function [*Smith*, 1990]. If these storms are observed from a fixed location in
 180 space, s , the maximum observed event at that location is given by

$$Z(s) := \max_{j \geq 1} \{U_j f(Y_j - s)\}, \quad s \in S.$$

181 The process, $Z(s)$, defines a stationary max-stable process. An illustration of this idea in one
 182 and two dimensions is given in **Figure 1** based on a Gaussian storm profile. **Figure 1(a)**
 183 displays $n = 5$ independent "storm" realisations, with the resulting process maxima
 184 highlighted (black line). The process maxima is not itself a realisation from a max-stable
 185 process as this requires $n \rightarrow \infty$ (suitably scaled) realisations. Similarly to univariate GEV
 186 models, the max-stable process limit can be used to approximate the distribution of the
 187 process maxima as n gets large. **Figure 1(b)** shows a realisation of a two-dimensional max-
 188 stable process. In both images, it is clear that two locations separated by a spatial distance
 189 within the range of the storm profile will tend to exhibit closely related data observations.

190

191 INSERT FIGURE 1 HERE

192

193 [15] Given a series of n observed data points $X_{i,k}$ for $i = 1, \dots, n$ at K spatial locations
 194 $s^1, \dots, s^K \in S$, the aim of a statistical analysis would be to fit a max-stable process using
 195 assumed parametric (or non-parametric) forms for the parameters $\mu(s)$, $\sigma(s) > 0$ and $\xi(s)$,
 196 while also estimating spatial dependence through the storm profile, f . However, for more
 197 than $K = 2$ spatial locations, the distribution function of the general max-stable process has
 198 no analytically tractable form [e.g. *Padoan et al.*, 2010], which thereby presents a problem
 199 for flexible and practical statistical model fitting through e.g. standard likelihood methods,
 200 and so ad-hoc procedures are usually adopted [e.g. *Smith*, 1990].

201

202 [16] When considering exactly $K = 2$ spatial locations, a bivariate class of spatial models
 203 with locations s^i and $s^j \in \mathbb{R}^2$ is available when the storm profile model, f , is a bivariate
 204 Gaussian density [*de Haan and Pereira*, 2006; *Smith*, 1990]. In this case the bivariate
 205 distribution function of $\{Z(0), Z(h)\}$ is

$$\Pr(Z(0) \leq z_i, Z(h) \leq z_j) = \exp \left[-\frac{1}{z_i} \Phi \left(\frac{a(h)}{2} + \frac{1}{a(h)} \log \frac{z_j}{z_i} \right) - \frac{1}{z_j} \Phi \left(\frac{a(h)}{2} + \frac{1}{a(h)} \log \frac{z_i}{z_j} \right) \right],$$

206 where $h = (s^j - s^i)'$, 0 is the origin, Φ is the standard univariate Gaussian distribution
 207 function, $a(h) = (h' \Sigma^{-1} h)^{1/2}$ and Σ is the (unknown) covariance matrix of f . From the
 208 above, the density function of $\{Z(0), Z(h)\}$ may be derived [e.g. *Padoan et al.*, 2010]. Note
 209 that $a(h)$ measures the strength of extremal dependence between s^i and s^j : $a(h) \rightarrow 0$

210 indicates complete dependence and $a(h) \rightarrow \infty$ represents complete independence [*de Haan*
211 *and Pereira, 2006*]. A general max-stable process with a Gaussian storm profile, f , is known
212 as a Gaussian extreme value process [*Smith, 1990*]. An alternative analytically tractable
213 bivariate distribution function, based on a different storm process, is given by Schlather
214 [2002].

215 [17] In order to model more than $K = 2$ spatial locations, Padoan et al [2010] proposed a
216 pairwise composite likelihood approach. Here an approximate likelihood function is
217 constructed as a product of density terms for each pair of locations s^i and s^j , $i \neq j$, where
218 the density is derived from the distribution function of $\{Z(0), Z(h)\}$, above. Subject to
219 suitable regularity conditions [*Padoan et al., 2010*], the maximum likelihood estimate of the
220 pairwise composite likelihood provides consistent and unbiased parameter estimates and
221 confidence intervals, when the standard maximum likelihood estimate of the full (but
222 intractable) max-stable likelihood model is unavailable. Perhaps most usefully, as this
223 approach is likelihood-based, the usual suite of statistical techniques become available
224 (suitably modified to account for the model mis-specification), resulting in a powerful and
225 flexible inferential framework. For example, it is then trivial to build in e.g. regression-based
226 forms for the parameters $\mu(s)$, $\sigma(s) > 0$ and $\xi(s)$ and estimate spatial dependence
227 parameters (e.g. Σ). See Padoan et al [2010] for further details, and the accompanying code
228 for model fitting in the *R* statistical programming language.

229 **2.2 Detecting trends in extremes: spatial dependence and sample size**

230 [18] We now present a synthetic study to assess the effect of spatial dependence and the
231 length of the observed data record in statistically detecting location trends in extremes. We
232 commence with a univariate analysis, where the data are drawn from a non-stationary GEV
233 distribution with a linear temporal trend so that $\mu(t) = \beta_0 + \beta_1 t$, with $t = 0, \dots, (n - 1)$,
234 where the indexing of the parameter μ is now with respect to time. The remaining parameters
235 are fixed at $\sigma = 1$ and $\xi = 0$, with $\beta_0 = 1$, unless stated otherwise. The aim is to determine
236 the value of β_1 which can be found to be statistically significant at the 5% significance level.

237 [19] Throughout this study, parameters are estimated using maximum likelihood, with the
238 univariate models implemented using the *R* package "*ismev*" (<http://www.r-project.org/>) [see
239 also *Coles, 2001*] and max-stable model with composite likelihoods through the *R* package
240 "*SpatialExtremes*" [*Padoan et al., 2010*]. For each setting, a total of 10,000 replicates were

241 generated, each of n observed sample points, and confidence intervals of the linear trend
242 parameter β_1 were estimated using the profile likelihood, as described by [Coles, 2001]. The
243 probability of detecting a trend was estimated as the proportion of the 10,000 replicates for
244 which the trend parameter was statistically significantly different from zero at the 5%
245 significance level. This is a practically useful means of presenting the results, as one often
246 wishes to know the probability of being able to detect a trend of given magnitude from an
247 observational record of finite length.

248 [20] The value of the trend coefficient, β_1 , that can be detected with 50%, 95% and 99%
249 probability is shown in **Figure 2(a)** as red solid, dashed and dotted lines, respectively, as a
250 function of the observed sample length n . As expected, the statistical power increases with
251 the sample length, so that smaller trends are detectable with larger datasets, with this increase
252 being approximately linear on a log-log scale. Furthermore, there also is a clear relationship
253 between the size of the β_1 coefficient and the probability of being able to detect this trend at a
254 given significance level (here 5%). For example, if it is desirable to have a 99% probability of
255 detecting a significant trend at the 5% significance level, it would be necessary to have nearly
256 twice the sample length (n) than if one would be satisfied with only a 50% probability of
257 detecting that trend. This type of reasoning becomes important when identifying data
258 requirements for studies into the detection of trends.

259 INSERT FIGURE 2 HERE

260 [21] The influence of different values of ξ is also shown in **Figure 2(a)** (solid lines) for a
261 50% probability of trend detection; this information is plotted in more detail in **Figure 2(b)**.
262 As can be seen, the greater the absolute value of ξ , the lower the value of β_1 that can be
263 detected at a given significance level, with this becoming particularly noticeable for larger
264 values of $|\xi|$. This occurs as holding the scale parameter fixed (at $\sigma = 1$) results in observed
265 data that are more clustered around the location (μ) for increasing $|\xi|$, than for $\xi = 0$, thereby
266 allowing more precise estimates of the location coefficients. As will be discussed further in
267 Section 4, in the present analysis we find values of ξ on average slightly positive (~ 0.17) with
268 a range of between -0.1 and 0.4 depending on the specific site. With sample sizes of 41 (sub-
269 daily gauges) and 96 (daily gauges), such an average value of ξ would allow for an
270 approximately 5% smaller value of β_1 to be detected compared to the case where $\xi = 0$.

271 [22] We now consider the influence of estimating a trend using a number of spatial locations,
272 assuming a fixed record length of $n = 100$ at each site. The data was generated at K random
273 locations within a unit square, under both the case of spatial independence (i.e. using the
274 spatial GEV model) as well as including different degrees of spatial dependence (i.e. using
275 the max-stable process model). Without loss of generality we assumed identical marginal
276 parameters across the spatial domain (i.e. $\mu(t) = \beta_0 + \beta_1 t$ with $\beta_0 = 1$, $\sigma = 1$ and $\xi = 0$).

277 [23] **Figures 2(c) and (d)** show the values of β_1 that have a 50% and 95% probability,
278 respectively, of being detected as a statistically significant trend (at the 5% level), as a
279 function of the number of spatial locations, K . In the case of spatial independence, the results
280 are qualitatively similar to the case of increasing sample length n : namely, the value of β_1
281 that can be detected at the 5% level decreases linearly as the number of spatial locations
282 increases. This is an obvious consequence of using more data. However, for a fixed number
283 of spatial locations, the presence of spatial dependence effectively reduces the amount of
284 independent data in the sample, thereby increasing the value of β_1 that can be detected. The
285 value of β_1 which can be detected at a given probability decreases more slowly with greater
286 dependence, highlighting that the inclusion of spatial information is most beneficial when
287 dependence is low. Interestingly, the rate of decrease of β_1 is approximately an order of
288 magnitude lower for adding spatial information compared with temporal information. This
289 clearly highlights that although spatial information significantly increases signal detectability,
290 it remains a poor substitute for increasing length of record when this information is available.

291 [24] Having demonstrated the advantages of explicitly considering spatial information in the
292 detection and attribution of trends in extremes, we now apply the max-stable process model
293 to the annual maxima of daily and sub-daily precipitation at different locations in Australia.
294 The data used for this analysis is described below.

295 **3. Data**

296 [25] Two alternative precipitation datasets were used in this analysis. The first was a subset
297 of Australia's pluviograph record, which provides measurements of precipitation in
298 increments of 6 minutes at 1397 locations around Australia [see description in *Westra et al.*,
299 2010]. For this study we considered only near-complete data over the period from 1965 to
300 2005. The data was carefully quality controlled, with only years included that had less than
301 15% of the within-year record classified as missing (including both 'missing' and

302 'accumulation' flags), as well as only including stations with less than 5 years missing.
303 Furthermore, annual cumulative precipitation plots for the sub-daily record were compared
304 visually with the annual cumulative plots for the daily-read gauged record collected at the
305 same location, and years for which the annual cumulative rainfall from the sub-daily gauges
306 departed from the annual cumulative rainfall from the daily gauges by more than 15% were
307 also classified as 'missing'. This filtering process yielded a total of 35 stations in Australia
308 with an average of 5.6% of years missing throughout the record across all stations, with
309 locations shown in **Figure 3**. Due to the sparse sampling of data throughout most of the
310 Australian continent, only the east Australian (EA) region was considered in this analysis
311 (comprising 30 stations), with the domain shown in **Figure 3**. At each station, series of
312 annual (block) maxima were derived for durations from 6 minutes through to 72 hours.

313 INSERT FIGURE 3 HERE

314 [26] The second precipitation dataset was the longer and more complete record obtained from
315 a quality-controlled daily-read dataset from 1910 to 2005, described more fully in [*Haylock*
316 *and Nicholls, 2000; Lavery et al., 1992*]. As described in these papers, the quality control
317 undertaken for this particular dataset included: investigation of the station history
318 documentation to remove stations with changes to observing practices, changes in the
319 exposure of the rain gauge, changes in rain gauge type, together with detailed statistical
320 testing to check station integrity.

321 [27] In more than 95% of cases, the station sites of the daily-read gauges were at different
322 locations to the sites for the sub-daily gauges described above, such that this dataset is largely
323 independent of the sub-daily dataset and therefore can be used as an independent means of
324 evaluating the sub-daily results. Only stations with less than 10% of years classified as
325 'missing' were considered, totalling 93 stations, with an average of 3.8% of years classified
326 as missing across all the stations. Due to the larger number of locations for daily data, the
327 southwest Western Australia (SWWA) and southeast Australia (SEA) regions defined in
328 **Figure 3** were also analysed in addition to the SE region considered for the sub-daily dataset.

329 [28] Dealing with missing data in all cases is difficult, and in particular in the case of the sub-
330 daily record for which there are limited sub-daily gauges nearby from which to infill. As
331 such, the primary quality control measure used here was to minimise the number of years
332 classified as missing. Of the data that was missing, three alternative infilling techniques were

333 adopted. The first involved substituting the mean annual maxima for that year across all the
334 remaining locations where data was available, after adjusting for the station mean. The
335 second technique involved substituting the mean annual maxima at that station across all
336 years with data. Finally a stochastic infilling technique was used in which annual maxima
337 were drawn from other years at the same station. Although none of these infilling techniques
338 can be expected to result in an accurate estimate of annual maximum precipitation for the
339 missing years, the use of three alternative techniques allows testing of the robustness of the
340 results described in subsequent sections to different treatments of missing data. In all cases,
341 the different infilling approaches did not make any substantive differences to any of the
342 results presented, with this being due to the relatively small number of records missing and
343 the benefits of using multiple spatial locations to limit the reliance on individual data points.
344 The results presented in the subsequent section are those derived using the first infilling
345 method.

346 [29] Of greater concern is the potential for inherent measurement biases in rainfall gauging.
347 In particular, the sub-daily rainfall gauges were replaced at many locations throughout
348 Australia in the 1990s and early 2000s, with the most common instrument change being from
349 a Dines pluviograph recorder to a Tipping Bucket Rain Gauge (TBRG). A detailed inventory
350 of gauge changes at each station was obtained from the Australian Bureau of Meteorology,
351 and two alternative approaches were considered to test whether such gauge changes
352 influenced the results. In the first approach, a univariate non-stationary GEV model with both
353 trend and step-change covariates was applied at each location (without consideration of
354 whether the trend or step change was statistically significant), with the date of the step change
355 selected based on the recorded date of the gauge change. Of the 30 sub-daily stations, step
356 changes at 17 of the locations were positive (suggesting that the trend after accounting for the
357 step change is smaller than by ignoring the step change), with step changes at the remaining
358 13 locations being negative. This result alone suggests the impact of the step change on the
359 trend results is likely to be minor, as one would expect any systematic biases due to shifting
360 from the Dines to the TBRG should result in step changes of the same sign and similar
361 magnitude. As a further means of evaluating the implication of any systemic effects due to
362 gauge changes, these step changes were then removed from each univariate time series, and
363 the max-stable process model was fitted to this adjusted data. The results from this analysis
364 were almost identical to the case where the step change was not accounted for. Finally, the
365 spatial GEV model was applied using only data from 1965-1990 (with this data being almost

366 completely before any instrumentation change) and the results were consistent with the
367 longer records except for wider confidence intervals due to the shorter record length. This
368 analysis shows that the implications of gauge changes do not appear to have any notable
369 impact on the results and conclusions presented in this paper, and therefore the remaining
370 analysis uses the complete record without explicitly modelling the implications of any gauge
371 changes.

372 [30] Finally, four separate temporal covariates were considered. The first represents a linear
373 trend, which is simply constructed as the sequence from zero to the number of observations
374 minus one. The second comprises a time series of average Australian annual land surface
375 temperature, obtained from the Australian Bureau of Meteorology
376 (http://www.bom.gov.au/cgi-bin/silo/cli_var/area_timeseries.pl). Here, this is used as a
377 surrogate of the land-surface temperature trend at the time of the storm event [*Hardwick-*
378 *Jones et al.*, 2010; *Lenderink and van Meijgaard*, 2008], due to the difficulties in averaging
379 land-surface temperature prior to each storm event when considering annual maxima at
380 multiple locations. The third represents the global average sea surface temperature time series
381 obtained from the International Comprehensive Ocean-Atmosphere Data Set (ICCOADS) sea
382 surface temperature anomaly record (http://jisao.washington.edu/data/global_sstanomts/), and
383 is used as a surrogate for the temperature of the moisture source region as discussed in
384 [*Hardwick-Jones et al.*, 2010]. Finally, the Southern Oscillation Index (SOI) is used as a
385 measure of the El Niño-Southern Oscillation (ENSO) phenomenon, and was obtained from
386 the Australian Bureau of Meteorology website
387 (<http://www.bom.gov.au/climate/current/soihtml.shtml>). With the exception of the linear
388 trend, each covariate is plotted from 1910 to 2005 in **Figure 4**.

389 INSERT FIGURE 4 HERE

390 **4. Results**

391 [31] We now apply the max-stable process model described in Section 2, to both the sub-
392 daily rainfall data for the east Australian domain, as well as the longer daily data record in
393 each of the three domains shown in **Figure 3**. The results of these analyses are described in
394 turn below.

395 **4.1 Sub-daily rainfall**

396 [32] We commence by considering the sub-daily precipitation observations at multiple point
397 locations in eastern Australia. By way of a preliminary analysis, we fit a non-stationary
398 univariate GEV model using a linear trend as the covariate as described in [Coles, 2001] to
399 each of the gauged locations, and then evaluate both the sign and the significance of this
400 trend. These results are shown for the 6-minute data in **Figure 5**, with red (blue) indicating
401 downward (upward) trends and filled circles indicating a statistically significant trend at the
402 10% significance level. As can be seen, although the magnitude of increase in extreme
403 precipitation varies considerably from location to location, there is no clear spatial pattern
404 associated with physiographic features such as coastlines or mountain ranges, nor any clear
405 relationship with major climate zones such as the winter-dominated rainfall patterns in the
406 southern parts of the country, summer-dominated monsoonal rainfall in the north, arid
407 climate in the centre and largely uniform rainfall in the southeast [e.g. see *Gallant et al.*, 2007
408 for a possible depiction of relevant climate zones for the detection of change to extreme
409 rainfall]. For the remainder of the sub-daily analysis we therefore focus on the east Australian
410 domain as a single homogenous region, as this maximises the number of stations to include in
411 the model.

412 INSERT FIGURE 5 HERE

413 [33] The location and scale parameters are modelled spatially as a linear function of
414 longitude, latitude, elevation and distance to coast (including the square root of these
415 variables), with the exact form of model derived using a forward stepwise selection procedure
416 informed by the (composite) likelihood ratio statistic. The shape parameter was modelled
417 uniformly across the domain, and was found to be on average slightly positive (~ 0.17) with
418 some variation depending on the storm burst duration that was analysed. The models that
419 were selected for each of the rainfall durations are shown in **Table 1**, and highlight that
420 complex combinations of the covariates are required to describe the spatial variability in
421 location and scale parameters. This is expected due to the large area covered by the domain,
422 and alternative formulations of predictors to estimate spatial variability in the GEV
423 parameters are likely to be equally valid. Nevertheless a comparison of the parameters
424 derived from the models given in **Table 1** with the point estimates of the parameters by
425 fitting a univariate GEV model to each location showed reasonable consistency, indicating
426 adequate spatial modelling of the max-stable process parameters. Furthermore, a sensitivity
427 analysis using slightly different sets of spatial covariates did not have a significant impact on

428 the value of the temporal covariates which are the focus of this study, and therefore the
429 models described in **Table 1** are considered suitable for the ensuing analysis.

430 [34] The magnitude of the temporal variation of extremes using each of the four covariates is
431 shown in **Figure 6**, using the sub-daily information for durations from 6 minutes to 72 hours.
432 The results using daily data in the east Australian domain from 1965 to 2005 are also
433 provided to check for consistency between the two datasets. The results are presented in
434 terms of: the percentage change from the beginning to the end of the record for the trend
435 covariate (**Figure 6a**); the percentage change per degree change in temperature for the
436 Australian temperature and global sea surface temperature covariates (**Figures 6b** and **6c**);
437 and the percentage change per standard deviation of the southern oscillation index (**Figure**
438 **6d**).

439 INSERT FIGURE 6 HERE

440 [35] To highlight the implications of spatial correlation, point estimates and confidence
441 bounds were generated assuming that the data are spatially independent (solid and dotted blue
442 lines), or modelling spatial dependence using the Gaussian extreme value process model of
443 [Smith, 1990] (solid and dotted red lines). The 90% confidence intervals were estimated using
444 the profile likelihood, with the likelihood statistics adjusted appropriately using the approach
445 described by [Rotnitzky and Jewell, 1990] due to the misspecification of the likelihood
446 function [Padoan et al., 2010]. As can be seen, in all cases the confidence interval using the
447 max-stable process model was wider than the confidence interval assuming spatial
448 independence, as expected from the results from the synthetic study described earlier.
449 Interestingly, although this effect was small for the sub-daily data, significant difference in
450 confidence intervals could be found for the daily data, highlighting that although more spatial
451 locations are available at the daily scale, this does not necessarily translate to a large increase
452 in information for the max-stable extreme value model.

453 [36] We now evaluate the implication of different temporal covariates on the east Australian
454 extreme precipitation series. Considering firstly the implications of a linear trend (**Figure 6a**),
455 it can be seen that short duration extreme rainfall has been increasing significantly over the
456 period of record from 1965 to 2005, with the mean annual maximum rainfall at the shortest
457 duration (6-minute) increasing by 18% (10% to 25%). This rate of increase is heavily
458 dependent on storm burst duration, with half hourly annual maxima increasing by 9.9%

459 (1.4% to 17%) and hourly rainfall increasing by only 4.6% (-3.1% to 12%) over this same
460 period. When looking at 24-hour rainfall, we do not find strong evidence of any trend, and at
461 longer-duration timescales there is some evidence of decreasing annual maximum rainfall.
462 Comparing these results with the daily annual maxima dataset, which as discussed were
463 derived from different types of gauges largely located in different point locations within the
464 same east Australian domain, we find the results to be consistent, with the trend in daily
465 maxima also not being statistically different from zero.

466 [37] To better understand the nature of these changes, the influence of two temperature-
467 related covariates – Australian annual average temperature (**Figure 6b**) and global sea
468 surface temperature (**Figure 6c**) – were also considered. At the shortest duration,
469 precipitation was found to increase by about 5.6% (-0.7 to 11.0%) per degree of Australian
470 annual average temperature, and 22.5% (10.8 to 33.7%) per degree of global sea surface
471 temperature. Given the increase in Australian annual average temperature has been less than a
472 degree over this period (e.g. CSIRO, 2007), these results show that average annual land
473 surface temperature change does not completely explain the observed increase of 18% over
474 this period as described in the previous paragraph. Furthermore, even at the 6-minute
475 timescale the relationship between extreme precipitation and Australian land surface
476 temperature is not statistically significant at the 5% significance level, suggesting that
477 average annual land surface temperature may be a poor predictor of change to extreme
478 precipitation. In contrast, the global sea surface temperature covariate shows a much stronger
479 relationship, and is significantly different from zero for all sub-hourly durations. Once again,
480 however, the increase in global SST was only about 0.4°C, yielding an expected increase due
481 to SST of about half the rate that has been observed based on the linear trend results. The
482 attribution of the strong increase in sub-daily precipitation therefore remains an area requiring
483 further investigation, potentially with the aid of dynamical modelling approaches to better
484 understand the large-scale atmospheric drivers of short-duration precipitation.

485 [38] Finally, the southern oscillation index was used as an indicator of the ENSO
486 phenomenon, the leading mode of climate variability affecting Australian rainfall at the inter-
487 annual timescale. The results of this analysis show that the strongest relationship between
488 annual maximum precipitation and the SOI occurs at the daily timescale, with an increase in
489 average 24-hour rainfall of 3.2% (0.97% to 5.4%), and for daily rainfall of 4.6% (2.3% to
490 7.1%) per standard deviation of the SOI. Interestingly, the relationship weakens for shorter

491 durations, and is no longer statistically significant for durations below about 3 hours,
492 suggesting that the SOI is most influential for longer-duration storm events.

493 **4.2 Daily rainfall**

494 [39] Although results from the daily rainfall record were presented for east Australian data in
495 the previous section, this was only based on information from 1965 to 2005 to ensure
496 consistency with the sub-daily record. Here we consider the full record from 1910 to 2005 for
497 east Australia, as well as two other regions shown in **Figure 3**. Only the results using the
498 max-stable process model are presented here, as the spatially independent extreme value
499 model is not likely to be realistic for the more densely gauged daily data.

500 [40] The results for the Australian temperature trend, global SST trend and the SOI are
501 presented in **Table 2**. The linear trend was not considered here as a linear change is expected
502 to be a poor representation of change to precipitation data over such a long period.
503 Considering east Australia, the results are consistent with the results presented in **Figure 6**
504 for each of the indices, with an absence of a statistically significant relationship between
505 daily annual maximum rainfall and Australian average temperature and the globally averaged
506 SST field, and with a statistically significant increase of annual maximum rainfall of 2.8%
507 per standard deviation of the SOI. The confidence intervals are approximately half as wide as
508 compared to those shown in **Figure 6**, highlighting the benefits of considering longer data in
509 providing more precise statistical inferences.

510 [41] Considering the remaining locations, it can be seen that there is a decrease in annual
511 maximum precipitation as a function of Australian temperature which is not statistically
512 significant in southeast Australia but is significant at the 90% level in southwest Western
513 Australia. This confirms the results of other studies such as [Alexander *et al.*, 2007; Gallant
514 *et al.*, 2007] who suggest that extremes in daily rainfall may be decreasing in areas where
515 there are large decreases in mean annual rainfall, with such decreases having been observed
516 in southwest Western Australia.

517 [42] Finally, there is a negative, but statistically insignificant, relationship with global SST at
518 all locations, and a positive and statistically significant relationship with the SOI, suggesting
519 that the SOI exerts a small but statistically significant influence on extreme daily rainfall in
520 all the regions analysed.

521 **Conclusions**

522 [43] In this paper we present one of the first applications of a non-stationary generalised
523 extreme value model based on max-stable process theory, in which data-level and parameter-
524 level dependence between precipitation data at individual point locations is explicitly
525 accounted for within the modelling framework. The advantages of such a modelling
526 framework were shown using a synthetic example, in which the probability of detecting a
527 statistically significant trend in the location parameter was evaluated for a range of record
528 lengths, number of spatial locations, and spatial dependence. In particular, the inclusion of
529 numerous spatial locations resulted in significant increases in the probability of being able to
530 detect a statistically significant trend, particularly when data-level dependence was low. As
531 data-level dependence increases, the max-stable process model was able to account for the
532 decrease in information via wider confidence intervals, whereas the spatial GEV model
533 would have resulted in unrealistically high levels of confidence in any temporal trends.

534 [44] Using this method, it was possible to detect a strong, statistically significant trend in sub-
535 daily (and particularly sub-hourly) precipitation across eastern Australia, with these increases
536 contrasting with the absence of any statistically significant changes at the daily timescale.
537 This finding is unsurprising for several reasons. Firstly, as described earlier the temperature
538 scaling of extreme precipitation in Australia also shows very different behaviour for short-
539 duration precipitation compared with daily precipitation, with maximum sensitivity with
540 surface temperature also occurring for sub-hourly durations [*Hardwick-Jones et al.*, 2010].
541 Furthermore, the sub-hourly timescale is generally regarded as the timescale for individual
542 convective cells within thunderstorm systems [*Wallace and Hobbs*, 2006], and thus is the
543 timescale which would be most sensitive to the moisture holding capacity of the atmosphere.
544 Finally, international studies using regional climate models also have found much stronger
545 scaling for hourly compared with daily precipitation [e.g. *Hanel and Buishand*, 2010].

546 [45] At the daily timescale, no change in annual maximum rainfall could be detected with the
547 exception of southwest Western Australia, where a 7.4% decrease in annual maximum
548 rainfall per degree of land surface temperature was detected. Although the choice of suitable
549 covariates to use for this type of analysis is likely to be debatable, the conclusions are
550 generally consistent with other studies which show an absence of significant changes to
551 extreme daily rainfall in most locations around Australia except for locations where the
552 annual rainfall is decreasing strongly, most notably southwest Western Australia [*Alexander*

553 *et al.*, 2007; *Gallant et al.*, 2007]. Finally, this study showed that although the influence of
554 ENSO on annual maximum rainfall in Australia is small, it is nonetheless detectable using the
555 max-stable process model described here.

556 [46] These results therefore affirm the importance of understanding changes in precipitation
557 at all timescales, and in particular at the scales of individual storm events rather than the daily
558 timescale for which data is more readily available. Although the availability of sub-daily data
559 in Australia is generally limited (with most records being too short, containing large
560 quantities of missing data, and including numerous changes to instrumentation which might
561 bias the results), making the application of this data for climate studies difficult, this paper
562 highlights that a careful statistical analysis that explicitly accounts for the spatial nature of
563 rainfall data, will be beneficial in recovering useful information from such an instrumental
564 record.

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693 **Tables**

694 **Table 1: Covariates used for spatial model, selected via a forward selection approach using a likelihood ratio test.**
 695 **Predictors include latitude, longitude, elevation and distance to coast, and the square root of these variables.**

Storm burst duration	Model
6 min	$\mu(x) = \alpha_0 + \alpha_1(\text{lat}) + \alpha_2(\text{lon}) + \alpha_3(\text{lon}^{1/2})$ $\sigma(x) = \beta_0 + \beta_1(\text{lat})$ $\xi(x) = \gamma_0$
12 min	$\mu(x) = \alpha_0 + \alpha_1(\text{lat}) + \alpha_2(\text{lon}^{1/2}) + \alpha_3(\text{lon}) + \alpha_4(\text{dist})$ $\sigma(x) = \beta_0 + \beta_1(\text{lat}) + \beta_2(\text{lon}^{1/2}) + \beta_3(\text{dist})$ $\xi(x) = \gamma_0$
30 min	$\mu(x) = \alpha_0 + \alpha_1(\text{lat}) + \alpha_2(\text{lon}^{1/2}) + \alpha_3(\text{lon}) + \alpha_4(\text{dist})$ $\sigma(x) = \beta_0 + \beta_1(\text{lat}) + \beta_2(\text{lon})$ $\xi(x) = \gamma_0$
1 hr	$\mu(x) = \alpha_0 + \alpha_1(\text{lat}^{1/2}) + \alpha_2(\text{lon}^{1/2}) + \alpha_3(\text{dist}^{1/2}) + \alpha_4(\text{lat})$ $\sigma(x) = \beta_0 + \beta_1(\text{lat}) + \beta_2(\text{lon}^{1/2})$ $\xi(x) = \gamma_0$
3 hr	$\mu(x) = \alpha_0 + \alpha_1(\text{lat}) + \alpha_2(\text{dist}) + \alpha_3(\text{lon})$ $\sigma(x) = \beta_0 + \beta_1(\text{lat}) + \beta_2(\text{dist}^{1/2}) + \beta_3(\text{lon}^{1/2})$ $\xi(x) = \gamma_0$
24 hr	$\mu(x) = \alpha_0 + \alpha_1(\text{lat}^{1/2}) + \alpha_2(\text{lon}^{1/2}) + \alpha_3(\text{dist}^{1/2}) + \alpha_4(\text{elev}^{1/2})$ $\sigma(x) = \beta_0 + \beta_1(\text{lat}) + \beta_2(\text{dist}^{1/2}) + \beta_3(\text{lon}^{1/2})$ $\xi(x) = \gamma_0$
72 hr	$\mu(x) = \alpha_0 + \alpha_1(\text{lat}^{1/2}) + \alpha_2(\text{lon}) + \alpha_3(\text{dist}^{1/2}) + \alpha_4(\text{elev})$ $\sigma(x) = \beta_0 + \beta_1(\text{lat}^{1/2}) + \beta_2(\text{dist}^{1/2}) + \beta_3(\text{lon}^{1/2})$ $\xi(x) = \gamma_0$

696

697 **Table 2: Relationship between daily rainfall from 1910-2005 and three covariates: Australian temperature, Global**
 698 **sea surface temperature (SST), and the Southern Oscillation Index (SOI). Relationship with temperature covariates**
 699 **is expressed as percentage change per degree change in the covariate, while relationship with SOI is expressed per**
 700 **standard deviation of the SOI. Numbers in parentheses represent the 5% and 95% confidence limits calculated using**
 701 **profile likelihood.**

	Australian Temperature	Global SST	SOI
Eastern Australia	-1.6 (-5.9 to 2.87)	-0.25 (-4.6 to 4.3)	2.8 (1.2 to 4.3)
Southeast Australia	-2.6 (-6.5 to 1.5)	-0.83 (-5.4 to 3.4)	2.0 (0.05 to 3.8)
Southwest Western Australia	-7.4 (-13.0 to 0.0)	-1.3 (-8.7 to 5.8)	2.6 (0.17 to 5.2)

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703

704 **List of Figure Captions**

705 **Figure 1:** Max-stable processes $Z(s)$ in one and two dimensions based on a Gaussian storm
706 profile. Panel (a) illustrates $n = 5$ Gaussian "storms" in one dimension (grey lines) with the
707 process maxima outlined in black. Panel (b) illustrates a max-stable process in two
708 dimensions $s = (s_1, s_2)$ with a positively correlated Gaussian storm profile.

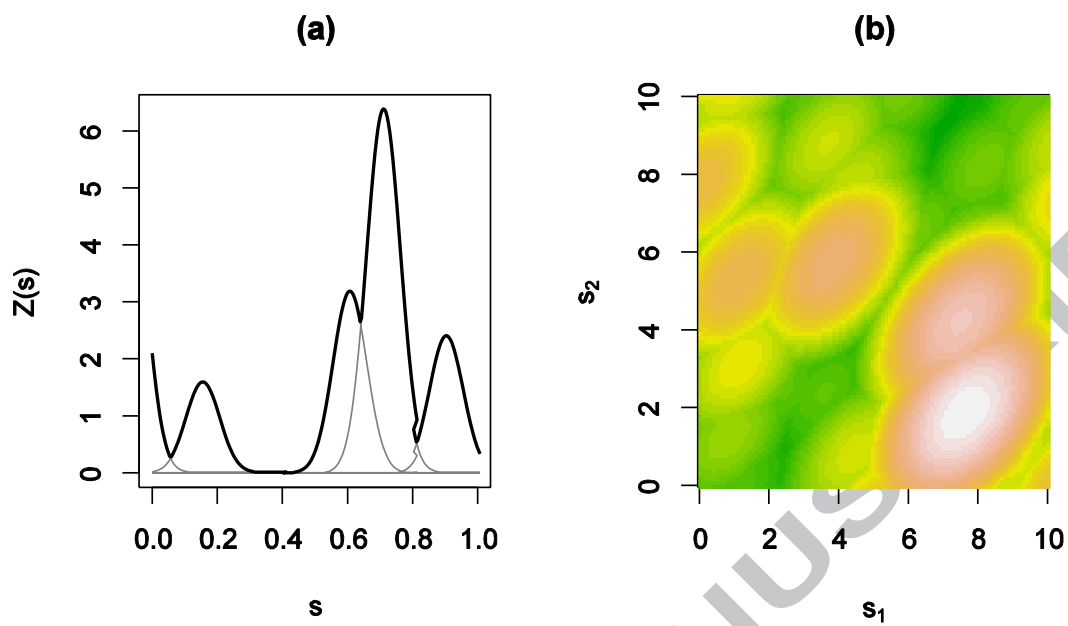
709 **Figure 2:** Probability of finding β_1 to be statistically significant at the 5% significance level.
710 (a) Implications of different sample lengths n , with different percentage change of detection
711 (i.e. 50%, 95% and 99% chance of detecting a statistically significant trend), and different
712 values of ξ ; (b) implications of ξ assuming 50% chance of detection; (c) implications of
713 number of spatial locations assuming sample length $n = 100$, assuming differing degrees of
714 spatial dependence, assuming 50% chance of detecting a statistically significant trend; and
715 (d) as with (c) but assuming 95% change of detecting a statistically significant trend.

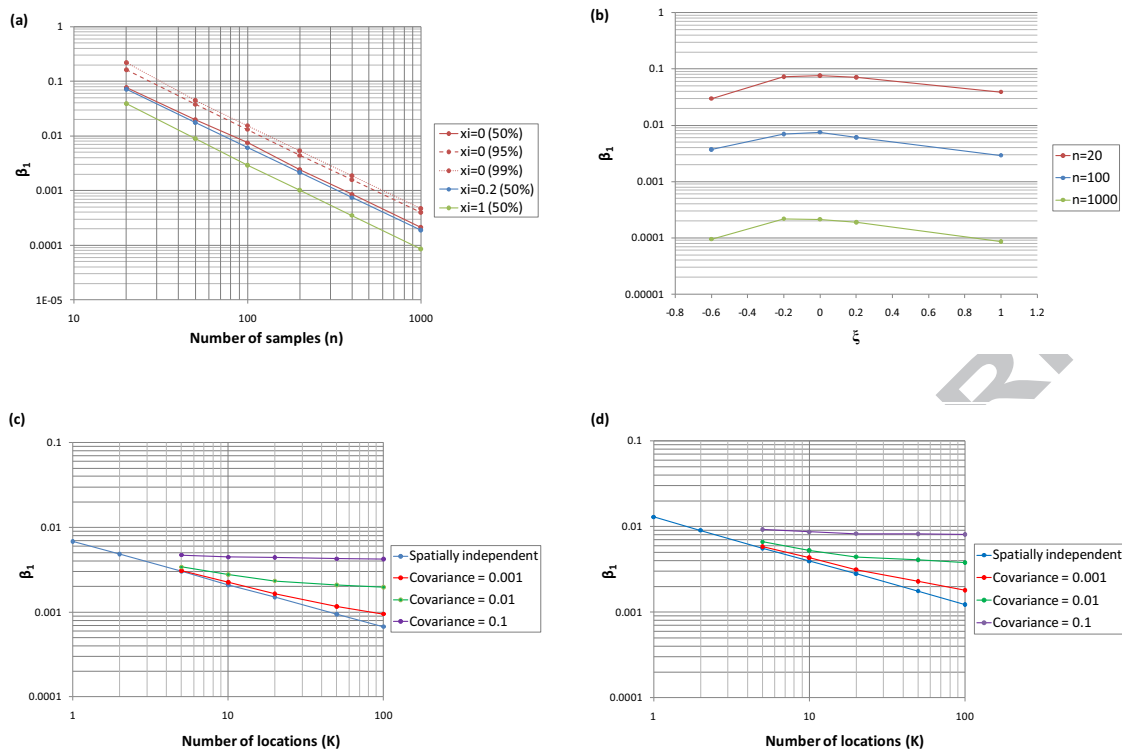
716 **Figure 3:** Location of quality-controlled pluviograph (blue dots) and daily-read (gray dots)
717 stations. The spatial extremes analysis was conducted for three regions for the daily data:
718 southwestern Western Australia (SWWA), southeast Australia (SEA) and eastern Australia
719 (EA), and for EA only for pluviograph data due to limited sampling density elsewhere.

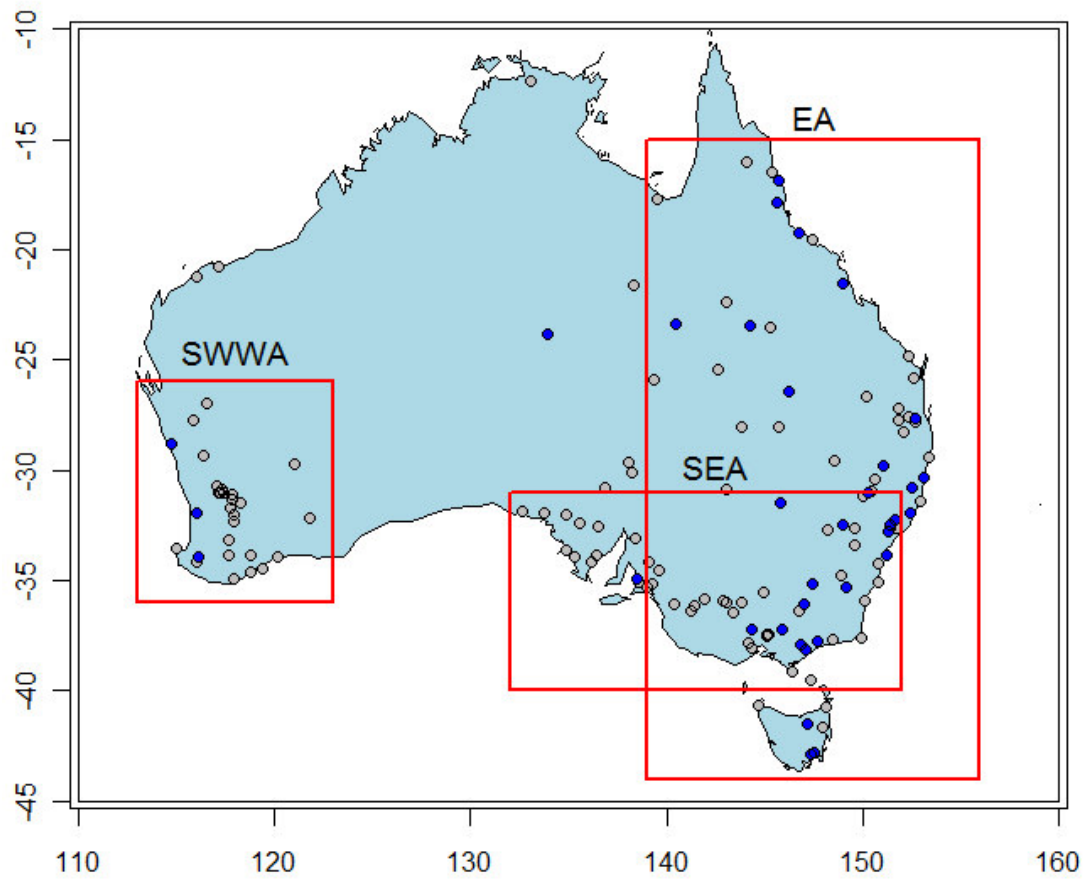
720 **Figure 4:** Covariates used in the study.

721 **Figure 5:** Non-stationary univariate GEV model with a linear trend as covariate applied to
722 each station for 6-minute annual maximum pluviograph data (left panel) from 1965 to 2005,
723 and the daily dataset (right panel) from 1910 to 2005. Red and blue indicate downward and
724 upward trends, respectively, with filled circles indicating the trend is statistically significant
725 at the 10% significance level.

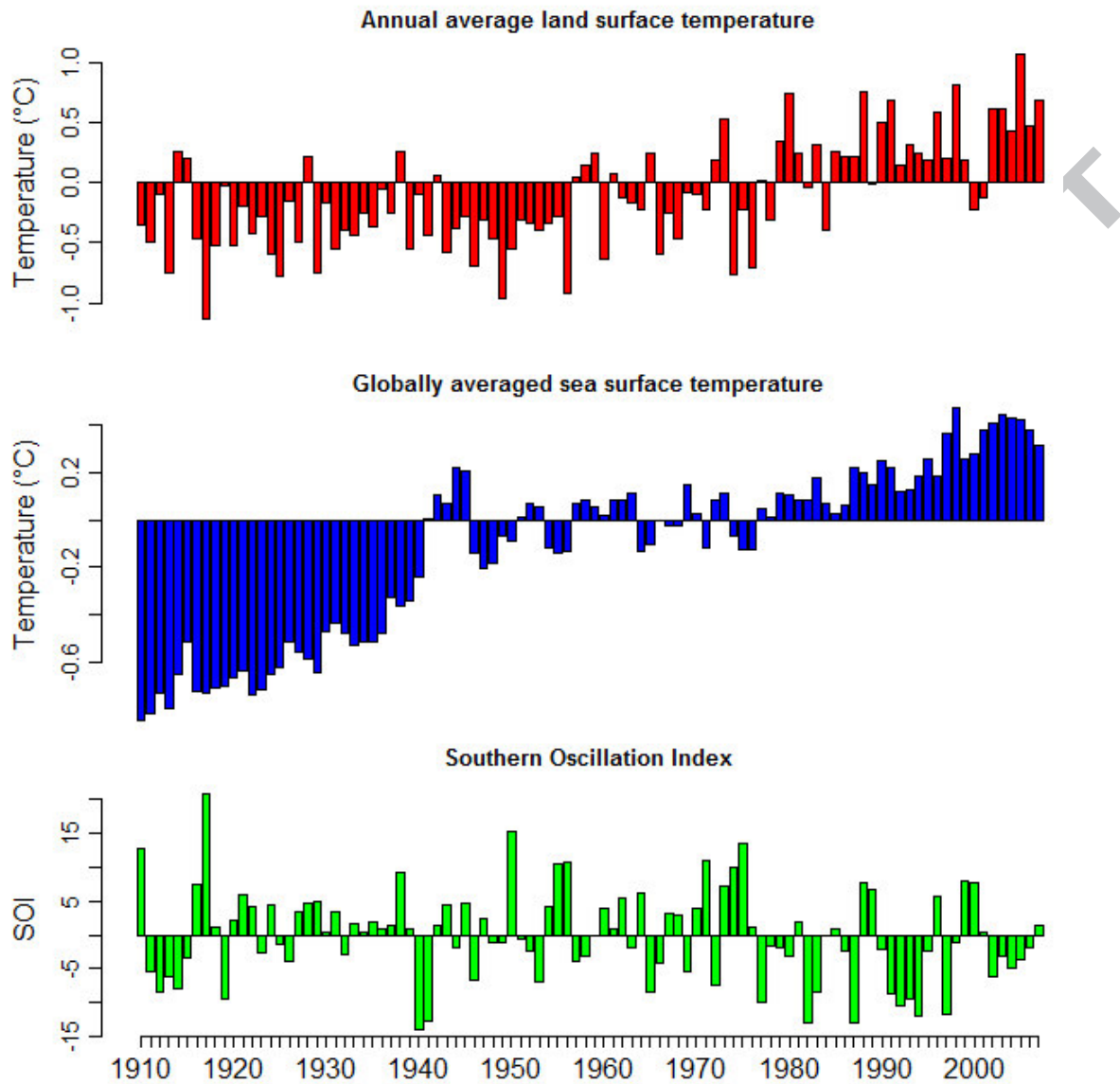
726 **Figure 6:** Relationship between sub-daily precipitation across east Australia for durations
727 from 6 minutes through to 72 hours, and the three temporal covariates. Solid blue line
728 represents the results from a spatial GEV model (ignoring spatial dependence), while solid
729 orange line represents results from max-stable model using the Smith spatial dependence
730 function. Dotted lines represent the 95% confidence interval. The outcomes from the daily
731 model is also shown (slightly offset for visual purposes), including red dots (spatial GEV)
732 and green dots (max-stable distribution), together with associated 95% confidence interval.

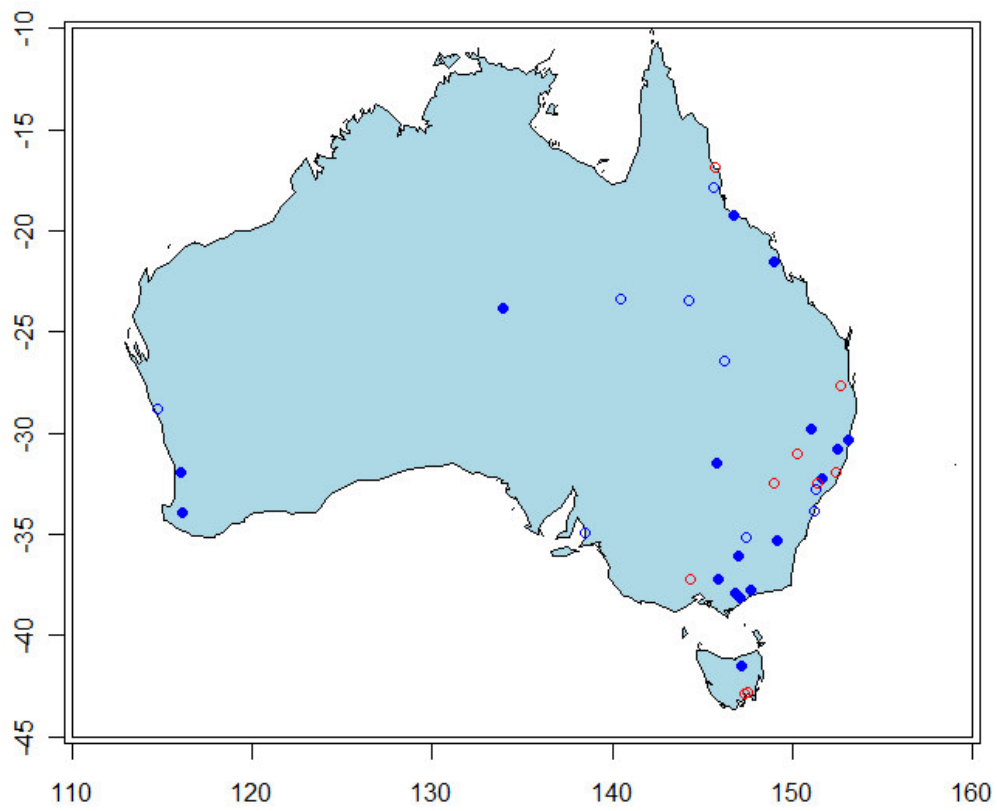


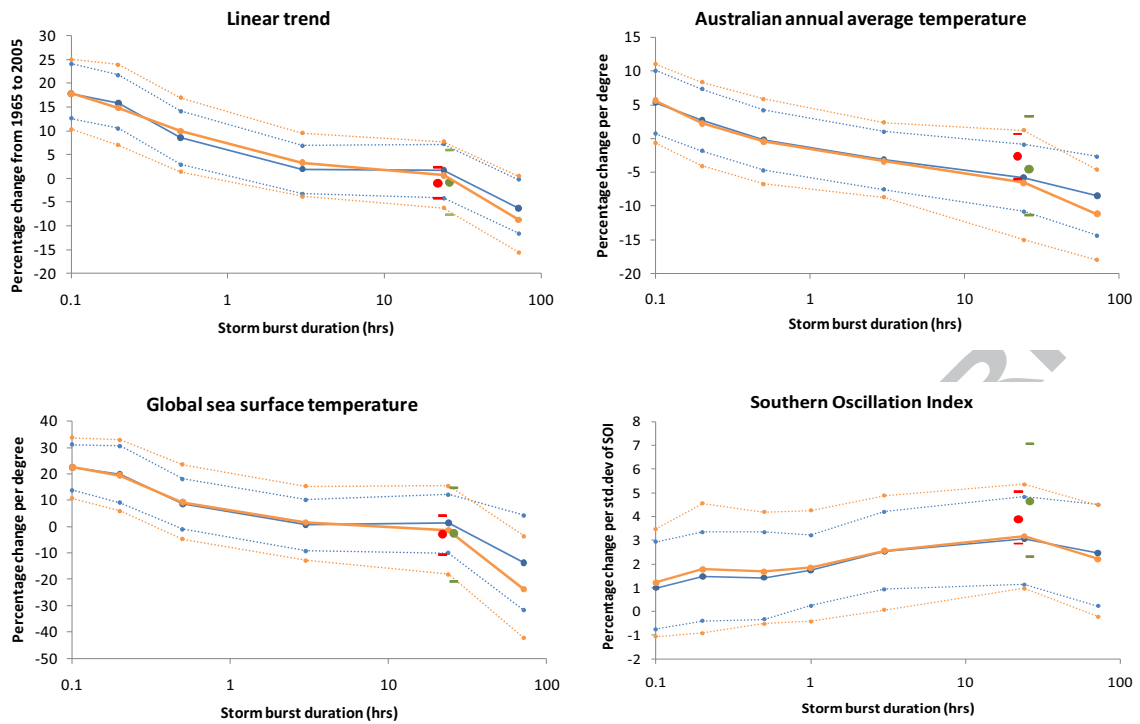




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- We demonstrate application of a max-stable process model using extreme rainfall data.
- We show how this model improves precision of inference by including spatial information.
- We find strong increases in sub-hourly extreme precipitation in East Australia.
- We find limited change to daily rainfall, except for a decrease in SW Australia.

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